

MERODUCTION

The preliminary considerations, which lead in 1957 to the decision to build a 7 GeV proton synchrotron in England, took place during the previous two years. The original intention was to produce a proton intensity of at least 1011 protons per second at an energy of 6.5 GeV and thus to provide a strong source of all the elementary particles known at that time.

The CERN and Brookhaven machines were then under construction. They embodied a number of new and difficult problems, and estimates of their intensity varied from a few times 10^9 protons per second. On the other hand, the bevatron was already producing about 10^{10} protons per pulse (once every 6 seconds) and seconds as clearly capable of considerable development along known lines. The large aperture of the weak focusing magnet is costly in steel and power but multi-turn injection allows a strong circulating beam to be set up before acceleration begins. The only sure way to get 1011 protons per second, in 1957, was with weak focusing.

A weak focusing machine was therefore chosen and an alternative proposal for a 12 GeV alternating gradient synchrotron was rejected in discussion with future users. Initially, it was intended to increase the strength of vertical focusing significantly by the use of spiral ridges, to give a Q_{v} of 3 while retaining the main properties of weak focusing machines, but this proposal was abandoned when severe dynamical problems were found to be associated with the presence of the straight sections which are essential. In the subsequent detailed design the energy was raised to 7 GeV and the intensity to about 5 x 1011 protons per second. The main Nimrod parameters are given in Table 1(1).

The magnet was designed with saturable polepieces so as to give a good field region matched to the required radial aperture which shrinks during acceleration, thus yielding considerable economy in magnet weight and power. A double walled vacuum rough vacuum and contains the magnet poles, which also provide its support. An inner vessel sits in the gap between the poles and is pumped to the necessary degree support and the walls of both can be thin and the maximum possible vertical aperture is thus available for the beam itself.

The magnet ring is divided into eight equal magnet segments or "octants", separated by straight sections which are required for beam injection and extraction systems, the r.f. accelerating cavity and beam control systems.

An injection energy of 15 MeV was chosen as one which could be achieved at reasonable cost while at the same time avoiding serious problems from gas scattering or from too low an initial magnetic field in the synchrotron magnet.

supply includes to obtain the maximum useful injection interval, the magnet power independently includes a facility for controlling the initial rate of rise of field to 1.5 ms are provided, the optimum time being found experimentally.

oscillations is thereby reduced to half the value produced by operation on the the programme control by the main magnet field plus curve correctors. The synchrotron r.f. system operates with a harmonic order of 4. Althoughtened a wide bandwidth in the system, the amplitude of the radial synchrotron control on both the frequency and phase of the accelerating voltage, in addition to condition that the strong beam induction electrodes are available to give servo Although this

Besides the use of internal targets, a Piccioni type system will be used for extracting the circulating beam. A second extraction system may be added during subsequent development. Both slow and fast beam spills will be available

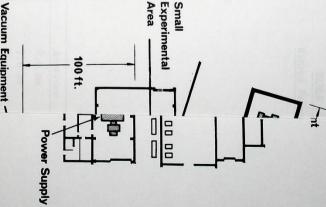
duots and tunnels are also provided for interconnection of services, power supplies and control systems. The magnet ring is housed in a large, circular, reinforced concrete building 200 ft in diameter. It is built partly below ground level and covered by 20 ft of earth mounding to serve as an additional radiation shield. The injector section accommodation for the vacuum pumps and for general services. Numerous underground circular internal walls to form sixteen cavities which are used to contain tangentially from the main building. The magnet is positioned on a large concrete monolith which takes the form of a partly hollow disc, reinforced by radial and has a separate hall, also covered by earth mounding, which projects almost An annular trench surrounds the magnet and provides

between the magnet room and the main experimental area, which is 60 ft in arc length and 28 ft wide. A small central pillar (1 ft wide, 8 ft long and 25 ft high) carries 7,500 tons and is the only bridge support which interferes with the positioning of beam lines into the experimental area. A feature of the Nimrod buildings is a massive concrete shielding bridge,

Separate buildings house the magnet power supply (a twin motor/alternator/cooling plant (including a block of four large evaporation coolers). A further building contains the main control room, orew rooms and offices for staff associated with the operation of the machine.

A simplified layout of some of the buildings is shown in Fig. 1(i) and a cut-figures showing individual parts of the machine are contained in the appropriate sections of this report. More detailed

A list of general articles on Mimrod is presented at the end of the report.



Vacuum Equipment ~

-Control Room



Experimental Area - Preparation Area

Scale in feet ble Chamber Area

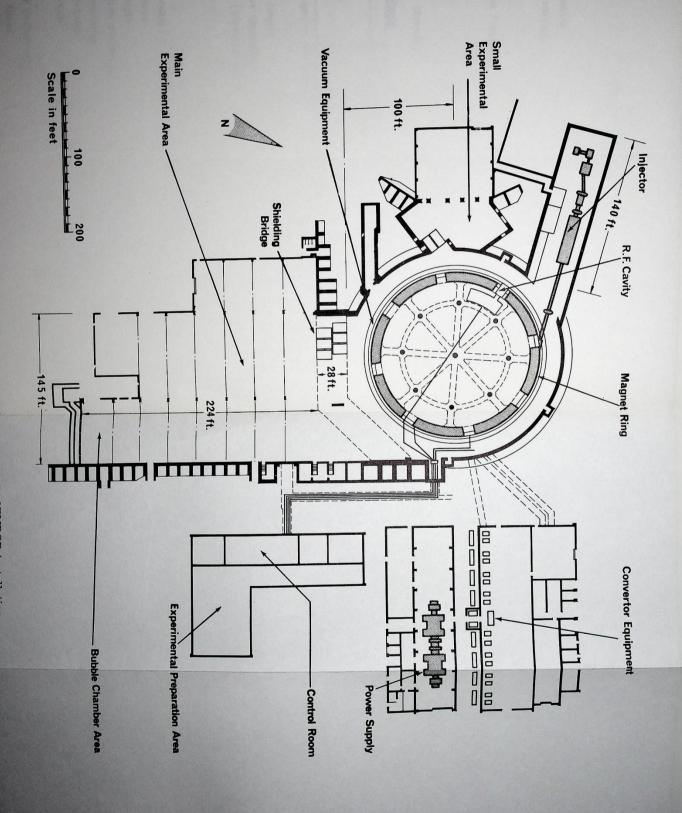


Fig. 1(i) A simplified plan showing the layout of the NIMROD installation.

TABLE 1(I)

Nimrod Parameters

Low Energy Drift Space INJECTOR Tank diameter (effective) Pre-Injector Tank length Ion Source Quadrupole gradients: Pulse repetition frequency R.F. pulse length Synchronous phase Frequency Beam current Plateau width (theoretical) Acceptance (area/ π) (+- +-, theoretical) Bunching factor (measured) Buncher drift length Buncher Q Peak r.f. voltage on buncher gap Third triplet Second triplet First triplet Last drift-tube First drift-tubes Focusing Beam emittance (Area/ π) Energy Focusing Pulse repetition frequency Pulse length Extracted beam current Extraction potential 8.9 cm 6.4 cm 7.6 cm Aperture 10 mA with buncher 3.0 x 10⁻² om rad at 600 keV 13.45 ш 3,700 gauss/cm 2/s maximum 2.5 ms 6 keV 2.2 115 Mc/8 1.4 m 1500 with external resistive loading 23 kV maximum 640 gauss/cm Up to 5 x 10⁻³ cm rad Electrostatic 600 keV 0.3μs and 5μs fixed 50μs - 1.5 ms variable 25-100 mA 2/s maximum 5-25 kV

240 gauss/cm 170 gauss/cm

Maximum gradient

480 gauss/cm

Drift-tube diameter No. of drift tubes

48 + 2 x 3

1.69 ш

28.2 cm

| Operating temperature | *Energy spread (total) | Peak r.f. voltage on output gap | Peak r.f. voltage on input gap | R.F. power at Q = 80,000 (theoretical) | Resonator Q (measured) | Output energy | Output aperture | Input aperture | |
|-----------------------|------------------------|---------------------------------|--------------------------------|--|------------------------|---------------|-----------------|----------------|--|
| 20°C | 300 keV | 680 kV | 140 kV | 800 kW | 80,000 | 14.9 MeV | 5.0 cm | 2.1 cm | |

| Peak r.f. voltage on de-buncher gap De-buncher Q (measured) De-buncher drift length | Third triplet) Fourth triplet) | First triplet | Focusing |
|---|----------------------------------|---------------|------------------|
| de-buncher gap d) th | 8.9 cm | 7.6 cm | Aperture |
| 240 kV 20,000 10.7 m | 430 gauss/om | 730 gauss/cm | Maximum gradiont |

ohromatic Inflector System

10.7 m

Number of elements Total deflection Achromatic mode Single crossover. + 25°

| [| العال | 4 | الله الله | 20 L | þ | Element | State of the late |
|----------|---------------|------------|------------|------------|-----------------|-------------|---|
| | Electrostatio | Shielded . | 'C' magnet | 'C' magnet | 'C' magnet | Туре | |
| | *10.5° | +26° | -36.5° | \$ 6° | 0-0 | Angle | |
| 0.0 B | т.124 ш | , | 0.7 = | 0.7 н | OTOTO TRANSPORT | Radius of | |
| 50 kV/cm | 5 kg | 8 kg | o kg | 8 kg | ing Field | Correspond- | |
| ص 9 | 5 0 | 6 cm | 6 cm | 6 cm | Radial | Aper | |
| 8 0 | . 8 0 | 9 om | 9 om | 9 ст | Vertical | Apertures | |

Cavity impedance :

at 1.4 Mc/s at 4.5 Mc/s at 8.0 Mc/s

3000 Ω 2000 Ω 8000 Ω

| | inflector | De-buncher | High energy drift space | Beam chopper | Linac | Buncher | D.C. gun | Location | ACUUM SYSTEM |
|---------------------|------------------------|-----------------------------|-----------------------------|-----------------------|-----------------------------|---------------------------|---------------------------|---------------------------|--------------|
| | 22 | T C | 2 | 1/8/CS | Up to 4 | 1 | 2 | Number of Pumps | |
| | | 9 in | 6 in | | 24 in | 9 in | 9 in | Size/ Speed | |
| | Ion pump | Mercury | Mercury | Ion pump | Mercury | Mercury | Mercury | Туре | |
| TODA DISEBUTE TO SE | of notioes digients Is | 1-5 x 10 ⁻⁶ torr | 1-5 x 10 ⁻⁶ torr | O THE PERSON NAMED IN | 1-2 x 10 ⁻⁶ torr | 1 x 10 ⁻⁶ torr | 3 x 10 ⁻⁶ torr | Working Pressure Range | |

R.F. SYSTEM

| Cavity impedance: at 1.4 Mc/s | biased to 8 Mc/s Q bias field | protons per pulse | Maximum stable synchrotron amplitude at injection Damped synchrotron amplitude at 7 GeV Radial betatron amplitude at 7 GeV (W.K.B. approximation) Accelerating cavity Q: at injection Mean | Energy spread at 7 GeV (assuming W.K.B. approximation) Phase oscillation frequency: at injection at 7 GeV Radial synchroty | Energy gain per turn: at 3 kilogauss/s at 20 kilogauss/s R.F. frequency error for 1 cm shift of closed orbit at injection Potential well depth: at injection, 3 kilogauss/s | Fortial frequency: at injection (14.9 MeV) at design energy (7 GeV) Harmonic number Synchronous phase angle | to a steady value of 20 kilogauss/s.) |
|-------------------------------|--|-----------------------------|--|---|---|---|---------------------------------------|
| S John Russ Sur | = 10 \ Peak r.f. flux = 60 gauss = 40 = 12 AT/om | 40 40 35 kw 1.6 kw | | 2.004 kc/s | | 355.6 kc/s 2.003 Mc/s | uss/s rising in 10 ms |

| General | MAGNET |
|---------|--------|
| | AND |
| | POWER |
| | SUPPL |
| | |
| | |
| | |

Polepieces

Proton kinetic energy: for $B_0=10$ kilogauss for $B_0=14$ kilogauss for $B_0=15.8$ kilogauss Design length of short straights (each) Number of straight sections Total straight section length (design) Magnetic field index, n (design) Design length of long straights (each) Mean orbit radius, Rm lagnet sector radius, Ko 4.77 GeV 7.00 GeV 8.00 GeV 0.60 3.353 m 8 (4 long, 4 short) 4.267 ш 30.480 m 23.633 ш 18.781 m

Total number of polepieces Total number of magnet yoke blocks Magnetic length of octant at Ro (design) 336

14.751 m

Magnet Coil

Number of pairs of polepisces per octant, type end 2 Number of pairs of polepieces per cotant, type MkII 12(6 each side of MkI's) Number of pairs of polepieces per octant, type MkI 28 (at centre of octant)

Steel allicon content Front edges of sectors lie on sector radius Block-block spacing at back edges Blook-block spacing at Ro Thickness of a yoke block (at Ro) Number of yoke blooks per octant Vertical yoke gap Total number of luminations per blook Thickness of block at back edge Blook-blook spacing at front edges Angle between centre lines of adjacent blocks Angle between centre lines of extreme blocks Weight of yoke block 42

1.074° 19.5 tons 19.355 ш 12.10 in (maximum) 14.253 in 44.03° 12.202 in 12.50 in (maximum) 13.859 in

> Rise time Peak current

80% minimum, 100% maximum 23.000 in

VI during flat-top R.M.S. current VI at top of current rise Magnet performance under standard pulse conditions Assumed voltage variation during decay Mean voltage during decay Assumed voltage variation during rise Mean voltage during rise Repetition rate Current decay time Buration of flat-top Magnet inductance (low currents) Coil resistance (at 50°C) Total weight of copper Length of mean turn on an octant Total copper cross-section Peak current (design) Number of coil turns Vertical gap between polepieces Vertical height of polepieces at Ro Radial length of magnetic profile of poleieces Silicon content of thick laminations Ratio of thin to thick laminations Sector radius of outside edge of magnetic profile of polepieces gilicon content of thin laminations Thickness of laminations - thick type Thickness of laminations - thin type Total number of laminations 9.1 WW -11.0 to -13.4 kV -11.7 kV 4550 A MW 80T 16.0 to 11.8 kV 13.9 kV 26/min 0.80 s 0.115 s 0.72 s 9150 A 155 in² 1.1 H 0.108 n 117 ft 250 ton 9150 42 10.09 in (minimum) 5.875 in 63ft 7.9 in 45.5 in 1.0% 3.5% 1:2 0.030 in nominal 0.020 in nominal 450 approximately



Overall average losses Nett energy loss/pulse Energy required during current decay: Energy delivered during flat-top Energy delivered to magnet during current rise: Iron loss (hysteresis) Eddy current loss Stored energy Copper loss Eddy current loss Stored energy Copper loss 1 - 8 2.22 MW 5.26 MJ 0.12 MJ CW 80.0 2.03 MJ 39 MJ 0.07 MJ 1.92 MJ 1.04 MJ 39. MJ